

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L3	1114	101/181.ccls.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/18 11:14
L4	292	101/182.ccls.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/18 11:14
L5	507	101/183.ccls.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/18 11:14
L6	0	101/181.ccls. drive adj device pulse adj train	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/18 11:15
L7	17	101/181.ccls. pulse adj train	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/18 11:15
L8	29	101/182.ccls. circuit	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/18 11:16
L9	13	101/183.ccls. pulse train	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/18 11:16

L24	1	(101/486.ccls. or 101/485.ccls. or 101/484.ccls.) (drive adj device and control and circuit and preset \$4 and position)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/18 11:21
L25	1	(101/486.ccls. or 101/485.ccls. or 101/484.ccls.) (drive adj device and control and circuit and preset \$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/18 11:21
L26	9	(101/486.ccls. or 101/485.ccls. or 101/484.ccls.) (drive adj device and control and circuit)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/18 11:21
L27	24	(101/486.ccls. or 101/485.ccls. or 101/484.ccls.) (drive adj device and control)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/18 11:22
S1	286	drive adj device print\$4 adj press	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/10 11:19
S2	98	drive adj device same print\$4 adj press	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/10 11:26
S3	65	drive adj device with print\$4 adj press	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/10 11:26
S4	1	drive adj device with print\$4 adj press lead\$4 adj axle	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/10 11:33

S5	2	drive adj device print\$4 adj press lead\$4 adj axle	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/10 11:34
S6	2	drive adj device with print\$4 adj press same circuit	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/10 11:38
S7	4	drive adj device same print\$4 adj press same circuit	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/10 11:38
S9	17	drive adj device same print\$4 adj press output with signal	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/10 11:47
S10	18	drive adj device same print\$4 adj press signal same drive unit	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/10 11:52
S11	0	drive adj device same print\$4 adj press signal same drive adj unit	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/10 11:52
S12	6	drive adj (device or system or control) same print \$4 adj press initial adj position (signal or output or determine adj position)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/12 10:11
S13	9	drive adj (device or system or control) same print \$4 adj press initial adj position	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/12 10:12

S14	18	drive adj (device or system or control) same print \$4 adj press (start or begin\$4 or initial) adj position	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/12 10:12
S15	88	drive adj (device or system or control) print\$4 adj press (start or begin\$4 or initial) adj (position or location)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/12 10:16
S16	73	drive adj (device or system or control) print\$4 adj press (start or begin\$4 or initial) adj (position or location) (signal or output or circuit)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/12 10:17
S17	17	drive adj (device or system or control) print\$4 adj press (start or begin\$4 or initial) adj (position or location) (signal or output or circuit) angular adj position	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/12 10:19
S18	17	drive adj (device or system or control) print\$4 adj press (start or begin\$4 or initial) adj (position or location) (signal or output or circuit) angular adj (position or location)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/12 10:20
S19	105	drive adj (device or system or control) print\$4 adj press (signal or output or circuit) angular adj (position or location) motor	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/12 10:49

S21	142	drive adj device method controlling adj unit	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/12 19:44
S22	1	drive adj device near5 method adj controlling adj unit	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/12 19:44
S23	41	circuit same (subcircuit or sub- circuit) same pulse adj train same output	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 10:32
S24	32	circuit with (subcircuit or sub- circuit) same pulse adj train same output	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 10:32
S25	11	circuit with (subcircuit or sub- circuit) with pulse adj train same output	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 10:33
S26	6	circuit with (subcircuit or sub- circuit) with pulse adj train with output	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 10:33
S27	43	circuit same (subcircuit or sub- circuit) same pulse adj train same (generat\$4 or creat \$4 or produc\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 10:35
S28	25	circuit same (subcircuit or sub- circuit) same pulse adj train with (generat\$4 or creat \$4 or produc\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 10:42

S29	7	(subcircuit or sub-circuit) with pulse adj train with (generat\$4 or creat\$4 or produc\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 10:56
S30	13	(subcircuit or sub-circuit) same pulse adj train same (generat\$4 or creat\$4 or produc\$4) same (number or plurality) same output	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 11:06
S31	1	circuit with pulse adj train with emulator circuit	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 12:04
S34	242	emulator adj circuit	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 12:04
S35	3	emulator adj circuit pulse adj train	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 12:04
S36	1	emulator adj circuit "101".clas.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 12:05
S38	50	circuit adj connect \$4 with client with network	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 12:36
S39	2	circuit adj connect \$4 with client with network drive adj (device or control or system)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 14:00

S40	2	circuit adj connect \$4 with client with network drive (drive adj device)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 14:01
S41	24	circuit adj connect \$4 with client with network control with system	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 14:02
S42	3	circuit adj connect \$4 with client with network same control with system	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 14:02
S43	202	circuit near3 connect\$4 with client with network	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 14:32
S44	28	circuit with connect \$4 with client with network same input same output	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 14:34
S45	2	circuit with connect \$4 with client with network same input same position	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 14:38
S46	8	circuit with connect \$4 with client with network same position	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 14:41
S47	0	circuit with connect \$4 with client with network same electron\$4 adj shaft	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 15:00

S48	13	"101".clas. electron \$4 adj shaft device (drive or system or control\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 15:01
S49	7	"101".clas. electron \$4 adj shaft device (drive or system or control\$4) angular adj position	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 15:01
S50	22	"101".clas. electron \$4 near3 shaft device near3 (drive or system or control\$4) angular near3 position	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 15:02
S51	27	print\$4 near3 press electron\$4 near3 shaft device near3 (drive or system or control \$4) angular near3 position	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 15:03
S52	0	print\$4 near3 press electron\$4 near3 shaft device near3 (drive or system or control \$4) angular near3 position initial near3 position	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 15:04
S53	83	pulse adj train with (fixed or definite) adj number	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 15:20
S54	103	pulse adj train with (fixed or definite) adj pulses	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 15:20

S55	102	pulse adj train with (fixed or definite) near3 number near3 pulses	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 15:21
S56	1	pulse adj train with (fixed near3 definite) near3 number near3 pulses	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 15:21
S57	8	pulse adj train with (fixed or definite) near3 number near3 pulses near3 circuit	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 16:09
S58	117	pulse adj train with parameter with (influence or change or adjust)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 16:28
S59	9	pulse adj train with parameter with (influence or change or adjust) with shape	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/13 17:00
S60	5	(second or another) adj circuit with (convert or change or alter or adjust or fix or modify or influence) with shape with (pulse adj train or signal)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/14 14:30
S61	2	"5,300,096".pn.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/14 14:37

S62	20	parameterize with signal with frequency	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 10:22
S63	3	parameteriz\$4 with (pulse adj train or output adj signal) with amplitude	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 10:46
S64	1	parameteriz\$4 with (pulse adj train or output adj signal) with height	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 10:49
S65	1	parameteriz\$4 with (pulse or signal) with height	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 10:50
S66	40	parameteriz\$4 with (pulse or signal) with (height or amplitude)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 10:54
S67	248	correlated with pulse with set	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 11:06
S68	73	correlated with pulse with set with output	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 11:07
S69	4	correlated with pulse with set with output with drive	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 11:07

S70	4	correlated with pulse with (set or group) with output with drive	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 11:08
S71	4	correlated with pulse with (set or group or collection) with output with drive	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 11:08
S72	26	pulse with (set or group or collection) with output with drive adj device	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 11:09
S73	5	pulse with (group or collection) with output with drive adj device	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 11:24
S74	35	pulse with (multiple or group or collection) with drive adj device	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 11:25
S75	39	set adj pulse with pulse near3 correlat\$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 11:28
S76	10	set adj pulse near3 correlat\$4 with signal	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 11:28
S78	62	control adj unit with preset with position with circuit	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 12:49

S79	2	control adj unit with preset with position with circuit with printing	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 13:01
S80	144	drive adj control with preset with position	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 13:23
S81	1	drive adj control with preset with position with (axel or arm)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 13:23
S82	1	drive adj control with preset with position with lever	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 13:23
S83	33	drive adj control with (setting or preset\$4) with position with (lever or axel or arm)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 13:24
S84	0	computer adj unit with circuit wiht detach with (chang \$4 or adjust\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 13:26
S85	0	computer adj unit with circuit with detach with (chang \$4 or adjust\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 13:27
S86	25	computer with circuit with detach \$4 with (chang\$4 or adjust\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 13:27

S87	3	computer with circuit near5 detach\$4 with (chang\$4 or adjust \$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 14:04
S88	80	drive adj control with preset with position with drive device	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 15:47
S89	4	drive adj control with preset with position with drive adj device	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 15:49
S90	56	drive adj control with preset near3 position	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 15:51
S91	43	register near3 control near3 system near3 particularly	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 15:59
S92	32	S91 control position	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 16:01
S93	24	S91 control position register adj control	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 16:02
S96	144	drive adj control with preset with position	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 16:24

S97	4	drive adj control with preset with position with (drive adj device)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 16:24
S98	4	drive adj control with preset with position "101". clas.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 16:24
S99	28	drive adj control\$4 with preset adj position	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 16:27
S101	89	drive adj control\$4 with (setting or preset\$4) with position same shaft	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 16:43
S102	0	axel adj position with preset	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 16:44
S103	69	shaft adj position with preset	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 16:44
S104	119	folding.ti. drive adj control	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 16:55
S105	2	folding.ti. drive adj control with preset	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 16:55

S106	2	fold\$4.ti. drive adj control with preset	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 16:56
S107	109	fold\$4.ti. drive adj control with fold\$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 16:56
S108	2	fold\$4.ti. drive adj control with fold\$4 with (setting or preset\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 17:08
S109	0	drive adj device control with independent adj master	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 17:15
S110	130	control with independent adj master	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 17:17
S111	14	control adj unit with independent adj master	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 17:17
S112	18	drive adj control with folding adj unit	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/17 17:26

12/ 18/ 2007 11:24:52 AM

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